

Yashika Patil

Minneapolis, MN | linkedin.com/in/yashika-patil | github.com/yashikapatil27

Professional Experience

MS Thesis Researcher, University of Massachusetts Dartmouth	Sep 2024 – Aug 2025
<ul style="list-style-type: none">Designed a novel visual reasoning framework for multimodal question answering in science, combining text and diagram understanding and RL with human feedback (RLHF).Fine-tuned large multimodal models (LLaVA-7B) on GPT-4-generated instruction data using QLoRA, 4-bit quantization, and hyperparameter optimization in PyTorch, improving accuracy and reducing hallucinations.Built end-to-end pipeline to integrate image captioning via BLIP-2 (VLM) into multimodal reasoning workflow.Optimized multi-GPU training on NVIDIA GPUs with CUDA mixed-precision and DeepSpeed-ZeRO, reducing compute cost while maintaining reliability.Implemented experiment tracking in Weights & Biases to log metrics, visualize performance trends, and compare model variants.Evaluated outputs with metrics such as BERTScore, achieving improved reasoning clarity and model accuracy over baseline Chain-of-Thought reasoning.	
R&D Intern, New Bedford Research & Robotics – New Bedford, MA	May 2024 – Aug 2024
<ul style="list-style-type: none">Developed and deployed vision-driven automation pipelines integrating ABB GoFa robotics and Cognex cameras, reaching 98% pick-and-place accuracy in real-time operations.Implemented predictive algorithms for shape recognition, centroid/edge detection, and 6-DOF manipulation, aligning with industrial automation requirements.Built trajectory-forecasting workflows to predict and grasp moving objects, demonstrating feasibility for conveyor-based applications.Prototyped custom robotic components using Rhino7 CAD and 3D printing, integrating ABB GoFa with a Cognex vision camera.Collaborated with industry partners on computer vision applications for quality inspection in food processing, applying ML workflows to practical production settings.Delivered R&D outputs under tight deadlines, presenting prototypes to cross-functional teams and external stakeholders.	

Skills

Robotics & Hardware: ABB GoFa, Robotic Arms, Cognex Cameras, Lab Automation, Hardware Troubleshooting, ROS 2

Programming & Systems: Python, C++, MATLAB, SQL, Git & GitHub, Linux, CAD/3D Printing, Shell Scripting, Debugging

Data & Automation Pipelines: ETL, Data Logging, Workflow Automation, Experiment Tracking, Predictive Algorithms

Collaboration & Documentation: SOP Development, Cross-functional Teamwork, Technical Reporting

Projects

RAGNovel: LangChain for Novel Summarization & Question Answering	Jan 2024 - Aug 2024
<ul style="list-style-type: none">Built a Retrieval-Augmented Generation system using LangChain, LLaMA2, and a vector store for literary QA.Combined extractive and abstractive methods to balance coherence and content fidelity in summaries.Focused on prompt-engineering, dynamic context handling to optimize LLM performance within token limits.Tested and compared the system's performance against standard techniques to ensure reliable results.	
Consumer Complaints: Text Classification	Sep 2023 - Dec 2023
<ul style="list-style-type: none">Developed NLP and ML pipeline for consumer complaints: tokenization, embedding (Word2Vec), and feature engineering.Cross-validated ML models (logistic regression, trees, k-means, FFN, RNN); best accuracy 85.9%.Trained FFN, RNN, bi-LSTM, and transformer models with hyperparameter tuning; bi-LSTM achieved 86.5% accuracy.Compared model performance using classification, regression, and clustering metrics to select the best architecture.	

Education

University of Massachusetts Dartmouth	Dartmouth, MA
<i>Master of Science in Data Science</i>	<i>Sep 2023 - Aug 2025</i>
Indian Institute of Science and Research Bhopal	Bhopal, India
<i>Bachelor of Science in Data Science & Engineering</i>	<i>Aug 2019 - May 2023</i>